

Gov 2002 - Causal Inference I

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Readings



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- ▶ Associations between variables, very famously, are not necessarily due to causation.
- ▶ Is there a relationship between the number of swimming accidents on a given day and the total sales of ice cream cones on that day? Yes. Is that relationship causal? probably not.

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- ▶ Here we have assumed that the treatment is binary, but we could generalize the potential outcomes to be a function of any value, $Y_i(a)$, where a can take any possible value.

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 1. No interference between units.
 2. Variation in the treatment is irrelevant.

A_i	Y_i	$Y_i(0)$	$Y_i(1)$
0	.63	.63	?
0	.52	.52	?
0	.55	.55	?
0	.47	.47	?
1	.49	?	.49
1	.51	?	.51
1	.43	?	.43
1	.52	?	.52

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- ▶ Average treatment effect (ATE):

$$\tau = E[\tau_i] = \frac{1}{N} \sum_{i=1}^N Y_i(1) - Y_i(0)$$

- Conditional average treatment effect (CATE) for a subpopulation:

$$\tau(x) = E[\tau_i | X_i = x] = \frac{1}{N_x} \sum_{i: X_i = x} Y_i(1) - Y_i(0),$$

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- ▶ Average treatment effect on the treated (ATT):

$$\tau_{ATT} = E[\tau_i | A_i = 1] = \frac{1}{N_t} \sum_{i: A_i = 1} Y_i(1) - Y_i(0),$$

where $N_t = \sum_i A_i$.

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- ▶ **Parametric identification** generally refers to the situation where the estimand is identified under a certain parametric model for the distribution of the data, but is not identified otherwise.
- ▶ A Heckman selection model is parametrically identified because estimating the causal effect in that case relies on the parametric assumption of normally distributed errors.

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- ▶ “What’s your identification strategy?” = what are the assumptions that allow you to claim you’ve estimated a causal effect?
- ▶ Estimation method (regression, matching, weighting, 2SLS, 3SLS, SEM, GMM, GEE, dynamic panel, etc) are secondary to the identification assumptions.

What is the selection problem?

- ▶ Start with *prima facie* effect, which is just the difference in means between those who take a treatment and those who do not.

$$E[Y_i|A_i = 1] - E[Y_i|A_i = 0] = E[Y_i(1)|A_i = 1] - E[Y_i(0)|A_i = 0]$$

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- ▶ The third line is what we call *selection bias*.
- ▶ Because of the selection bias, without further assumptions we say that the ATT is *unidentified*.

Randomization solves the selection problem

- ▶ Randomizing the treatment means that the treated group is a random sample from the population and the in-sample mean is equal to overall mean:

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- ▶ This is not the same as the treatment being independent of the observed outcomes ($Y_i \perp\!\!\!\perp A_i$).

- ▶ How does randomization help identify the causal effect? It ensures that there is no selection bias. Note that, because of ignorability:

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- ▶ Thus, the ATE is nonparametrically identified: no matter what assumptions we make about the distribution of Y , we can always estimate it with the difference in means.

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- ▶ Sometimes instead of making inference about a population, we would rather make inference about the sample that we actually observed.
- ▶ This might make more sense in a lot of political science, where we don't have a larger super population in mind. This is similar to the arguments made about Bayesian inference.

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- ▶ The SATE is the in-sample version of the ATE (which we sometimes call the PATE to distinguish it from the SATE) and for any given sample, won't equal the PATE.
- ▶ SATE varies over samples from the population. What's this distribution called?

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- ▶ The usual difference in means estimator can consistently estimate both the ATE and SATE, but the variance of that estimator is smaller when estimating the SATE. This makes sense as we are treating the sample as fixed, so that variation doesn't enter into the sampling distribution.
- ▶ Unfortunately, it is usually impossible to estimate the variance of the sampling distribution for the SATE, but we know it's smaller than the variance for the ATE, so we can use that as a conservative estimator.

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- ▶ Need to justify our claims by assumption and by theory instead of by direct manipulation.

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- ▶ How can we figure out if ignorability holds in some case? Untestable, but can infer from other assumptions. . .

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- ▶ They are *acyclic* because there are no cycles: a variable cannot cause itself, either directly or through cycles.
- ▶ Causal Markov assumption: conditional on its direct causes, a variable V_j is independent of its non-descendants.

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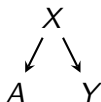
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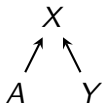


- ▶ Two variables connected by common causes will have a marginal associational relationship. That is, in the above example $\Pr[Y = 1|A = 1] \neq \Pr[Y = 1|A = 0]$.

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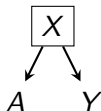
- ▶ Let's look at another situation:



- ▶ Here, X is a *collider*: a node that two arrows point into.
- ▶ Are A and Y related? No.
- ▶ Imagine that A is getting the flu and Y is getting hit by a bus. Both of these might cause us to be in the hospital, but knowing that I have the flu doesn't give me any information about whether or not I've been hit by a bus. The flow of association is blocked by a collider.

Conditioning on a confounder

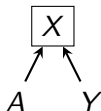
- Above we have shown how marginal associations flow over paths, but what about relationships between variables within levels of a third variable? We can represent conditioning on a variable by drawing a box around it.



Conditioning on a variable is on a causal path or on a variable that is a common cause (above), will block the association that flows over that path.

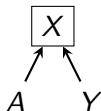
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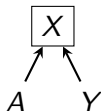
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- ▶ To see why this is the case, let's go back to the flu, getting hit by a bus example.

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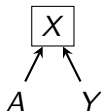
- ▶ Conditioning on a collider (a common consequence) actually opens the flow of association over that path, even though before there was none:



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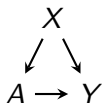
- ▶ To see why this is the case, let's go back to the flu, getting hit by a bus example.
- ▶ Conditional on being in the hospital, there is a negative relationship between the flu and getting hit by a bus.
- ▶ To sum up: associations flow over paths (causal or noncausal) that don't contain a collider. These associations can be blocked by conditioning a variable on the path that is not a collider. We'll come back to these properties later when we talk about the back-door criteria.

Backdoor paths and blocking paths

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- ▶ Here there is a backdoor path $A \leftarrow X \rightarrow Y$, where X is a common cause for the treatment and the outcome.

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- ▶ A path is *blocked* if (a) we control for or stratify a non-collider on that path OR (b) we do not control for a collider.
- ▶ Thus, in the above sample, if we condition on X , then the backdoor path is blocked.

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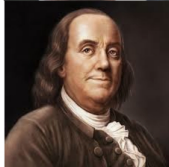
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- ▶ The first situation is only plausible in a randomized experiment, but the second might be plausible in observational studies as well.
- ▶ The backdoor criterion is fairly powerful. It can tell us (1) if there is confounding given this DAG, (2) if it is possible to remove the confounding, and (3) what variables to condition on to eliminate the confounding.

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- ▶ “All backdoor paths blocked” \equiv conditional ignorability
- ▶ **No free lunch:** DAG must be correctly specified

Readings



Estimating causal effects under no unmeasured confounders

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- ▶ Another assumption we'll need here is the following overlap (or positivity) assumption: $0 < \Pr(A = 1|X) < 1$.
- ▶ The assumption of selection on the observables is what allows us to identify causal effects.
- ▶ But we still have to estimate them. And given ignorability, there are several choices we can make for the estimation of causal effects.

Conditional ignorability and identification

- ▶ We can identify the CATE with conditional ignorability:

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- ▶ We can just use the within-levels of X difference in means to estimate the CATE. There are a number of ways we could estimate those conditional expectations, though. We'll cover a few in this class.

Regression

- ▶ When we look at a textbook, we often see regression defined without respect to causality. There is talk of the $\hat{\beta}$ estimator being “biased,” but it isn’t always clear what the “correct” specification would look like. There is an implicit assumption of causality, but no formal definitions. This can obscure the identification of the causal effects of interest. Today, we’ll see if we can estimate causal effects with regression.

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- ▶ We will show that under certain conditions, a regression of the outcome on the treatment and the covariates can recover a causal parameter, but perhaps not the one in which we are interested.
- ▶ We have shown in past weeks that these effects are identified when ignorability holds. Angrist and Pischke call this the conditional independence assumption (CIA).

Linear constant effects model, binary treatment

- ▶ Experiment: with a simple experiment, we can rewrite the consistency assumption to be a regression formula:

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- Note that if ignorability holds (as in an experiment) for $Y_i(0)$, then it will also hold for v_i^0 , since μ^0 is constant. Thus, this satisfies the usual assumptions for regression.

- ▶ Let's now say that ignorability holds only conditional the covariates, so $Y_i(a) \perp\!\!\!\perp A_i | X_i$. We will assume a linear model for the potential outcomes:

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- ▶ Because we are assuming the effect of A is constant here, the η_i are the only source of individual variation and we have $E[\eta_i] = 0$. We can use the consistency assumption to write this as a linear regression model:

$$Y_i = \alpha + \tau A_i + \eta_i.$$

- ▶ Assume that η_i is linear in the covariates $\eta_i = X_i' \gamma + \nu_i$.
(strong assumption)

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- ▶ Thus, a regression where A_i and X_i enter linearly will correctly estimate the average treatment effect, τ , since the residual of the linear regression is independent of the covariates:

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- ▶ Note that nothing we have done changes if A_i were continuous or ordinal (so long as linearity holds)

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- ▶ When we have to condition on some variables, things get difficult.

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- Focus on the case where X_i is univariate and binary and we can generalize from there.

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- ▶ \tilde{A}_i is the residual from a regression of A_i on the X_i or $\tilde{A}_i = A_i - E[A_i|X_i]$.

Heterogeneous effects (cont'd)

- ▶ A regression of Y_i on the treatment and covariates is the same as a regression of the $E[Y_i|X_i, A_i]$ on the treatment and covariates. Thus, in the above expression, we can replace Y_i with $E[Y_i|X_i, A_i]$.

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- ▶ For the regression coefficient, we take the average weighted by the conditional variance of treatment in that stratum.

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- ▶ Why does the OLS estimator weight by the conditional variance of the treatment? OLS is a minimum-variance estimator.
- ▶ Gives more weight to strata with lower expected variance in their estimates. That is, it gives higher weight to more precise within-strata estimates. When are these estimates going to be more precise? When the treatment and control group are roughly the same size and so the variance is maximized.
- ▶ When does $\tau = \tau_R$? When $\tau(x) = \tau$ is constant across the strata of the covariates.

Nonparametric regression

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- ▶ An alternative regression estimator is sometimes called the imputation estimator. and
- ▶ Impute the values of $Y_i(1)$ and $Y_i(0)$ for each unit, using a regression, and then taking the average of the differences between these imputations as the estimator for the ATE.

Nonparametric regression

- ▶ Let $\hat{\mu}_a(x)$ be a consistent estimator for $\mu_a(x) = E[Y_i(a)|X = x]$. We could always run a saturated (in X_i) linear regression in the treated and control groups separately as this estimator.

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- ▶ Can go even further by weakening parametric assumptions on $\mu_a(x)$.

Nonparametric regression R example

```
## load in lalonde data
data(LL, package = 'cem')

reg.0 <- lm(re78 ~ age + education + black + married,
            data = LL, subset = treated == 0)
reg.1 <- lm(re78 ~ age + education + black + married,
            data = LL, subset = treated == 1)

muhat0 <- predict(reg.0, newdata = LL)
muhat1 <- predict(reg.1, newdata = LL)

mean(muhat1 - muhat0)
```

```
## [1] 806.9
```

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- ▶ Otherwise, we may have to subclassify/coarsen the data.

Stratification on the propensity score

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- ▶ Rosenbaum and Rubin (1983) showed that if we correctly estimate the e_i , stratifying on e_i is the same as stratifying on the full X_i .

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Any set of variables that blocks all the backdoor paths from A_i to Y_i .
- ▶ Check balance within strata of \hat{e}_i or use automated/nonparametric tools for estimating \hat{e}_i .

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 $\frac{1}{N} \sum_i \mathbb{I}(X_i = x)$.
- ▶ For subclassification on the propensity score, you simply weight by the size of each stratum.

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- ▶ One way to think of this approach is that we are “imputing” the missing values $Y_i(0)$ for the treated units, using control units with very similar values of X_i .
- ▶ Remember that matching doesn't justify a causal effect, ignorability does.

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- ▶ Exact balance: $\Pr(X_i = x | A_i = 1) = \Pr(X_i = x | A_i = 0)$ for all values of x .
- ▶ This is because in the matched data, for every treated unit, there is one (and, in this case, only one) control unit with the same exact value of X_i . The two groups must have the same distribution in X_i .

Why exact matching works

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6. Calculate the effect of the treatment on the outcome in the matched datasets.

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- ▶ As long as you only drop control units, matching will estimate the ATT. But if we drop any treatment units, then we are estimating a different quantity of interest depending on the sample that remains. Sometimes we call this the feasible ATE.
- ▶ There's a bias-variance tradeoff in the number of matches—more matches means the set of matches might be worse, but you have more of them so the estimates are better.

Weighting

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- ▶ Taking a weighted difference in means or using a WLS with these as weights can estimate the ATE.
- ▶ Nice because it avoids having to model the relationship between X and Y , but you do have to model the propensity score.

Wrap-up

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- ▶ Randomization breaks selection bias.
- ▶ Without randomization we have to rely on assumptions about conditional ignorability.
- ▶ With this selection on observables assumption, we can use a couple of different techniques for estimating causal effects.

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- ▶ Not necessarily. If we have access to “natural experiments,” we can sometimes make more limited inferences.
- ▶ We'll start down that path next week with instrumental variables.

SATE vs PATE (more info)

- ▶ Once we assign some groups to treatment and some to control we do not actually observe $Y_i(1)$ and $Y_i(0)$ and so we cannot actually observe SATE. We can, however, estimate it:

$$\hat{\tau}_S = \frac{1}{n_t} \sum_{i:A_i=1} Y_i - \frac{1}{n_c} \sum_{i:A_i=0} Y_i$$

- Note that, conditional on the sample, the only variation in $\hat{\tau}_S$ is from the treatment assignment. Unconditionally, there are two sources of variation: the treatment assignment and the sampling procedure.

- We can show that, with a completely randomized experiment assignment, $\hat{\tau}_S$ is unbiased for τ_S and, in fact, τ :

$$\begin{aligned} E[\hat{\tau}_S|S] &= \frac{1}{n_t} \sum_{i:A_i=1} E[Y_i|A_i=1, S] - \frac{1}{n_c} \sum_{i:A_i=0} E[Y_i|A_i=0, S] \\ &= \frac{1}{n_t} \sum_{i:A_i=1} E[Y_i(1)|S] - \frac{1}{n_c} \sum_{i:A_i=0} E[Y_i(0)|S] \\ &= \frac{1}{n_t} n_t E[Y_i(1)|S] - \frac{1}{n_c} n_c E[Y_i(0)|S] \\ &= E[Y_i(1) - Y_i(0)|S] = \frac{1}{n} \sum_{i \in S} Y_i(1) - Y_i(0) = \tau_S \end{aligned}$$

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- ▶ By the law of iterated expectations, we also know that $E[E[\hat{\tau}_S|S]] = E[\tau_S] = \tau$. Thus, the difference in means is also unbiased for the PATE.

- It turns out that the sampling variance of the difference in means estimator is:

$$V(\hat{\tau}_S|S) = \frac{S_c^2}{n_c} + \frac{S_t^2}{n_t} - \frac{S_{\tau_i}^2}{n},$$

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- ▶ Here S_c^2 and S_t^2 are the in-sample variances of $Y_i(0)$ and $Y_i(1)$, respectively. We can use sample variances within levels of A_i to estimate these.
- ▶ The last term, $S_{\tau_i}^2$ is the in-sample variance of the individual treatment effects.
- ▶ Obviously, we don't observe any individual treatment effects, so we can't estimate a sample variance of this quantity. If the treatment effect is constant, then this term equals zero.

- It turns out that the overall variance of the estimator is simply:

$$V(\hat{\tau}_S) = \frac{\sigma_c^2}{n_c} + \frac{\sigma_t^2}{n_t},$$

which can be estimated with this simple variance estimator:

$$\hat{V} = \frac{\hat{s}_c^2}{n_c} + \frac{\hat{s}_t^2}{n_t}$$

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- This estimator is unbiased for the variance of the difference in means in the population OR a conservative estimate of the variance of the difference in means in the sample.

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