

## Gov 2000: 8. Simple Linear Regression

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*Where are we? Where are we going?*

- Last week: motivating the idea of regression and deriving an estimator for the parameters of a linear regression model.
- This week: investigating the properties of the least squares estimator and the assumptions of the linear regression model.

### REVIEW

The (population) simple linear regression model can be stated as the following:

$$\mu(x) = E[Y_i | X_i = x] = \beta_0 + \beta_1 x$$

This describes the data generating process in the population. We refer to  $Y_i$  as the dependent variable and  $X_i$  as the independent variable. Here,  $\beta_0$  and  $\beta_1$  are the population intercept and population slope, respectively. These are what we want to estimate.

This week we will take a conceptual turn and interpret this CEF as **structural** or **causal**. That is, we assume that  $\beta_1$  here is the effect of an additional unit of  $X_i$  holding all other factors fixed. This is a departure from last week, when we said that the linear projection existed in a very general way. It still does and so we can always run a regression of  $Y_i$  on  $X_i$ . But we usually use the linear regression model to investigate causal relationships, so it is useful to know under what assumptions we can do this.

This can get confusing because there is little distinction in textbooks or applied work between the linear model as a projection/CEF/associational and the linear model as structural/causal.

In a given data set, we can use OLS to obtain the estimated or sample regression function:

$$\hat{\mu}(X_i) = \hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$$

Here,  $\hat{\beta}_0$  and  $\hat{\beta}_1$  are the estimated intercept and slope and  $\hat{Y}_i$  is the fitted value of the regression. In a simple regression, the fitted value is just the  $y$ -value of the line for a unit's particular value of  $X_i$ . We also have the residuals,  $\hat{u}_i$  which are the differences between the true values of  $Y$  and the fitted value:

$$\hat{u}_i = Y_i - \hat{Y}_i.$$

You can think of the residuals as the prediction errors of our estimates.

## GOALS

Overall, the goal of this part of the course is to learn how to run and read regression: \* Mechanics: how to estimate the intercept and slope? \* Properties: when are these good estimates? \* Uncertainty: how will the OLS estimator behave in repeated samples? \* Testing: can we assess the plausibility of no relationship ( $\beta_1 = 0$ )? \* Interpretation: how do we interpret our estimates?

- A more narrow goal is to understand everything from an R regression output:

```

ajr <- foreign::read.dta("../data/ajr.dta")
out <- lm(logpgp95 ~ logem4, data = ajr)
summary(out)

##
## Call:
## lm(formula = logpgp95 ~ logem4, data = ajr)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -2.71304 -0.53326  0.01954  0.47188  1.44673
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  10.66025    0.30528   34.92 < 2e-16 ***

```

```
## logem4      -0.56412    0.06389   -8.83 2.09e-13 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.7563 on 79 degrees of freedom
## (82 observations deleted due to missingness)
## Multiple R-squared:  0.4967, Adjusted R-squared:  0.4903
## F-statistic: 77.96 on 1 and 79 DF,  p-value: 2.094e-13
```

## MECHANICS OF OLS

As we saw last week, ordinary least squares (OLS) is an estimator for the slope and the intercept of the regression line. We talked last week about ways to derive this estimator and we settled on deriving it by minimizing the squared prediction errors of the regression, or in other words, minimizing the sum of the squared residuals:

$$(\hat{\beta}_0, \hat{\beta}_1) = \arg \min_{b_0, b_1} \sum_{i=1}^n (Y_i - b_0 - b_1 X_i)^2$$

In words, the OLS estimates are the intercept and slope that minimize the sum of the squared residuals.

This defines the procedure to find the estimates, but we can also solve for the estimated slope and intercept. These formulas provide some intuition. The intercept equation tells us that the regression line goes through the point  $(\bar{Y}, \bar{X})$ :

$$\bar{Y} = \hat{\beta}_0 + \hat{\beta}_1 \bar{X}$$

The slope for the regression line can be written as the following:

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})}{\sum_{i=1}^n (X_i - \bar{X})^2} = \frac{\text{Sample Covariance between } X \text{ and } Y}{\text{Sample Variance of } X}$$

Thus, the higher the covariance between  $X$  and  $Y$ , the higher the slope will be. Furthermore, because the sample variance of  $X_i$  will always be non-negative, negative covariances will imply negative slopes and positive covariances will imply positive slopes. It is helpful for you to think about what happens when  $X_i$  and/or  $Y_i$  don't vary?

### *Mechanical properties of OLS*

Later we'll see that under certain assumptions, OLS will have nice statistical properties. But some properties of OLS are mechanical in the sense that they are just a function

of how we estimated the slope and intercept. Each of these can be derived from the minimization problem that OLS solves. The residuals will be 0 on average:

$$\frac{1}{n} \sum_{i=1}^n \hat{u}_i = 0$$

The residuals will be uncorrelated with the predictor ( $\widehat{\text{cov}}$  is the sample covariance):

$$\widehat{\text{cov}}(X_i, \hat{u}_i) = 0$$

The residuals will be uncorrelated with the fitted values:

$$\widehat{\text{cov}}(\hat{Y}_i, \hat{u}_i) = 0$$

Note that these are properties of the estimated residuals,  $\hat{u}_i$ , not the true errors,  $u_i$ !

*OLS slope as a weighted sum of the outcomes*

One useful derivation that we'll do moving forward is to write the OLS estimator for the slope as a weighted sum of the outcomes.

$$\begin{aligned} \hat{\beta}_1 &= \frac{\sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})}{\sum_{i=1}^n (X_i - \bar{X})^2} \\ &= \frac{\sum_{i=1}^n (X_i - \bar{X})Y_i}{\sum_{i=1}^n (X_i - \bar{X})^2} - \frac{\sum_{i=1}^n (X_i - \bar{X})\bar{Y}}{\sum_{i=1}^n (X_i - \bar{X})^2} \\ &= \frac{\sum_{i=1}^n (X_i - \bar{X})Y_i}{\sum_{i=1}^n (X_i - \bar{X})^2} \\ &= \sum_{i=1}^n W_i Y_i \end{aligned}$$

Where here we have the weights,  $W_i$  as:

$$W_i = \frac{(X_i - \bar{X})}{\sum_{i=1}^n (X_i - \bar{X})^2}$$

This is important for two reasons. First, it'll make derivations later much easier. And second, it shows that is just the sum of a random variable. Therefore it is also a random variable.

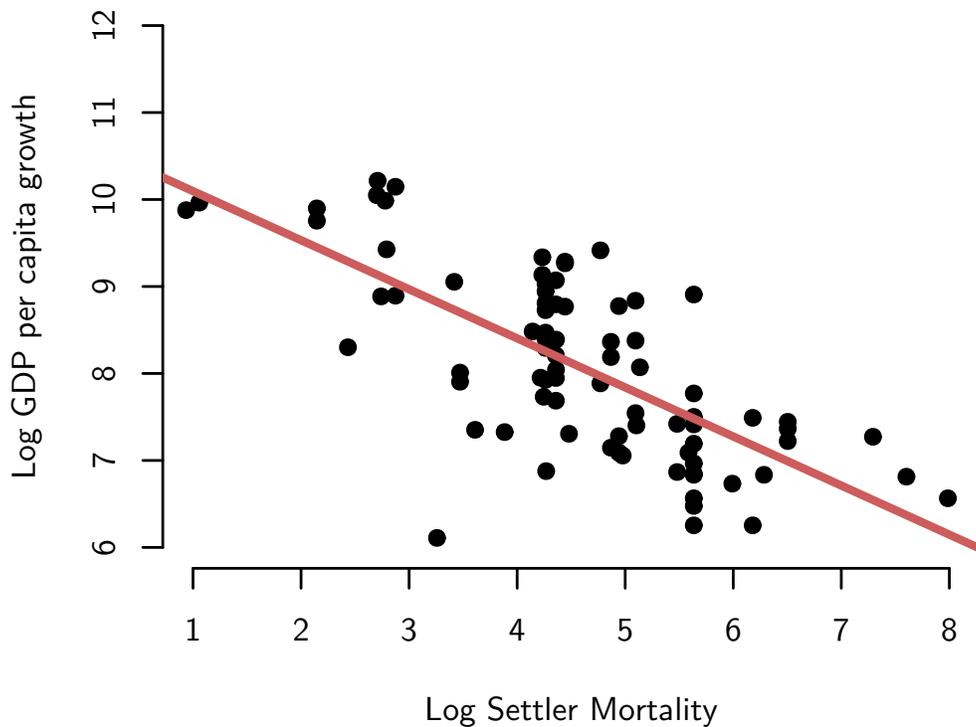
## PROPERTIES OF THE OLS ESTIMATOR

### *Sampling distribution of the OLS estimator*

- Remember: OLS is an estimator—it's a machine that we plug data into and we get out estimates. Just like the sample mean, sample difference in means, or the sample variance. It's a more complicated estimator, to be sure, but it still has the same basic structure as the others. It has a sampling distribution, with a sampling variance/standard error, etc.

Let's simulate some data to get a sense for how the sampling distribution of the OLS estimators works. To do this, we're going to pretend that the AJR data represents the population of interest and we are going to take samples from it to see how the regression line varies from sample to sample. (Note that this is just for demonstration since we'll never actually have the whole population). First, let's plot the population regression line:

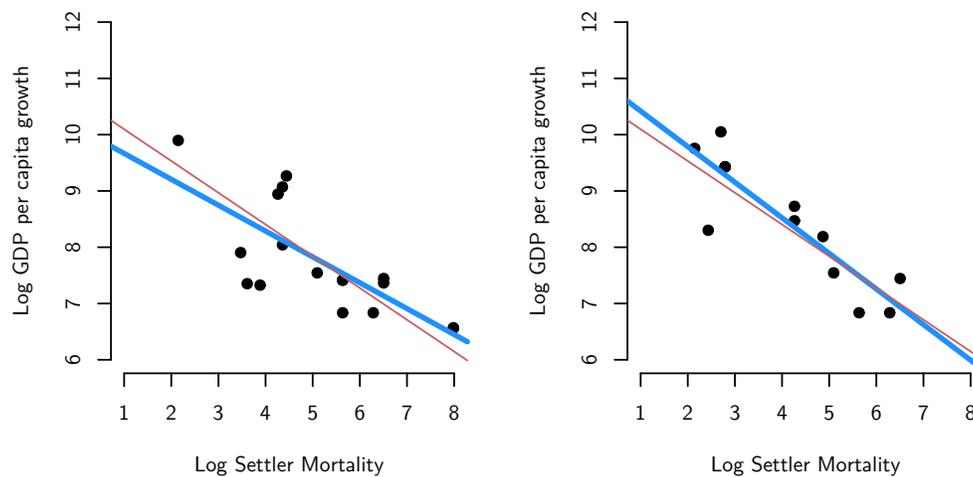
```
plot(ajr$logem4, ajr$logpgp95, xlab = "Log Settler Mortality", ylab = "Log GDP per capita growth", pch = 19, bty = "n",
     abline(lm(logpgp95 ~ logem4, data = ajr), col = "indianred", lwd = 3))
```



Now, let's take two random samples of size  $n = 30$  from this "population" and the plot the results, with the true population line overlaid:

```
set.seed(02143)
par(mfrow = c(1,2))
ajr.samp <- ajr[sample(1:nrow(ajr), size = 30, replace = TRUE),]
plot(ajr.samp$logem4, ajr.samp$logpgp95, xlab = "Log Settler Mortality", ylab = "Log GDP per capita growth", pch = 1)
abline(lm(logpgp95 ~ logem4, data = ajr.samp), col = "dodgerblue", lwd = 3)
abline(lm(logpgp95 ~ logem4, data = ajr), col = "indianred", lwd = 1)

ajr.samp2 <- ajr[sample(1:nrow(ajr), size = 30, replace = TRUE),]
plot(ajr.samp2$logem4, ajr.samp2$logpgp95, xlab = "Log Settler Mortality", ylab = "Log GDP per capita growth", pch = 1)
abline(lm(logpgp95 ~ logem4, data = ajr.samp2), col = "dodgerblue", lwd = 3)
abline(lm(logpgp95 ~ logem4, data = ajr), col = "indianred", lwd = 1)
```



Note how in our two samples, the slope and the intercept are not exactly the same as in the population. In the first, the estimated intercept is *lower* than the population intercept, while in the second the estimated intercept is higher. In the first sample, the estimated slope is closer to 0 than the true slope. In the second sample, it's more negative than the true slope. **This is just due to random sampling!**

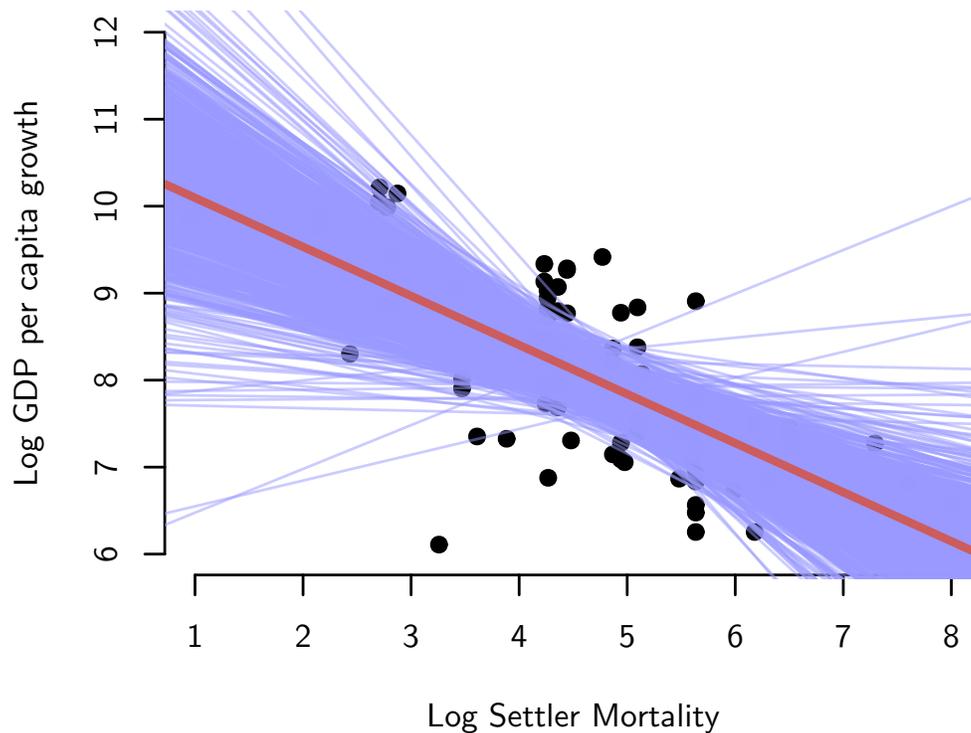
Now let's repeat this process 1000 times to see how the slopes and intercepts vary in lots of repeated samples:

```
set.seed(02143)
true.reg <- lm(logpgp95 ~ logem4, data = ajr)
sims <- 1000
```

```

inters <- rep(NA, times = sims)
slopes <- rep(NA, times = sims)
plot(ajr$logem4, ajr$logpgp95, xlab = "Log Settler Mortality", ylab = "Log GDP per capita growth", pch = 19, bty
for (i in 1:sims) {
  ajr.samp <- ajr[sample(1:nrow(ajr), size = 30, replace = TRUE),]
  this.reg <- lm(logpgp95 ~ logem4, data = ajr.samp)
  abline(this.reg, col = rgb(0.6, 0.6, 1, alpha = 0.5), lwd = 1)
  inters[i] <- coef(this.reg)[1]
  slopes[i] <- coef(this.reg)[2]
}
abline(true.reg, col = "indianred", lwd = 3)

```



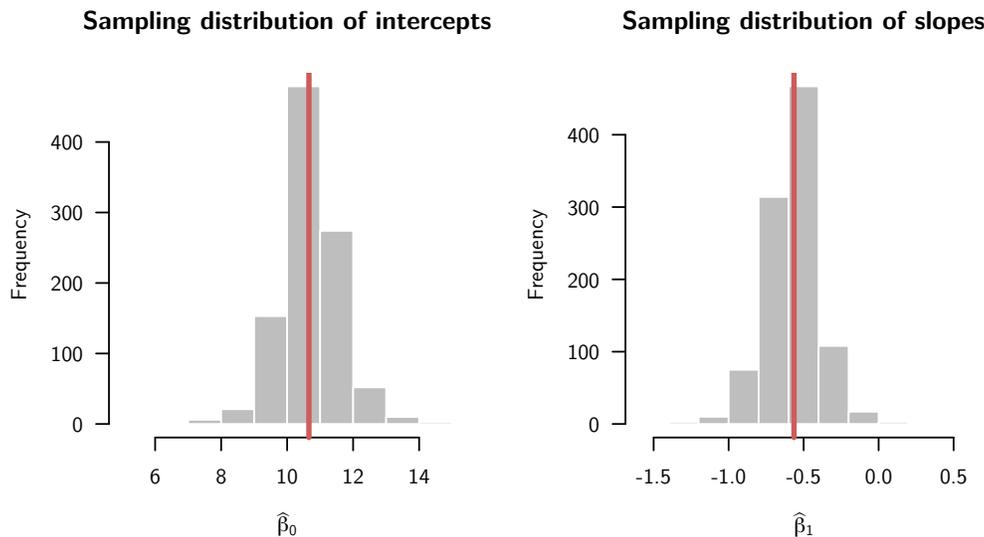
You can see that the estimated slopes and intercepts vary from sample to sample, but that the “average” of the lines looks about right. We can look at the sampling distribution of the parameters separately to see that this is about right:

```

par(mfrow = c(1,2), las = 1)
hist(inters, xlab = expression(hat(beta)[0]), main = "Sampling distribution of intercepts", col = "grey", border

```

```
abline(v = coef(true.reg)[1], col = "indianred", lwd = 3)
hist(slopes, xlab = expression(hat(beta)[1]), main = "Sampling distribution of slopes", col = "grey", border = "v
abline(v = coef(true.reg)[2], col = "indianred", lwd = 3)
```



The sampling distribution of the OLS estimators are centered roughly around their true value. Remember that we call this property unbiasedness of the estimators. Here's the question: will OLS always be unbiased? Under what assumptions will it be unbiased or consistent?

### *Unbiasedness*

What assumptions did we make to prove that the sample mean was unbiased? Just one: that we had a random or iid sample from the population. We'll need more than this for the regression case, especially since we would like to interpret these differences causally.

Generally we'll need different assumptions to derive different properties of the OLS estimator. For unbiasedness, we'll need the following assumptions:

1. Linearity
2. Random (iid) sample
3. Variation in  $X_i$
4. Zero conditional mean of the errors

*Assumption 1: Linearity*

**Assumption 1** - The population regression function is linear in the parameters:

$$Y = \beta_0 + \beta_1 X_i + u$$

Here,  $u$  is the unobserved error or disturbance term that represents all factors influencing  $Y$  other than  $X$ . Note that this error is different than the CEF or linear projection error from last week because we are now interpreting the coefficients structurally. Violation of the linearity assumption:

$$Y_i = \frac{1}{\beta_0 + \beta_1 X_i} + u_i$$

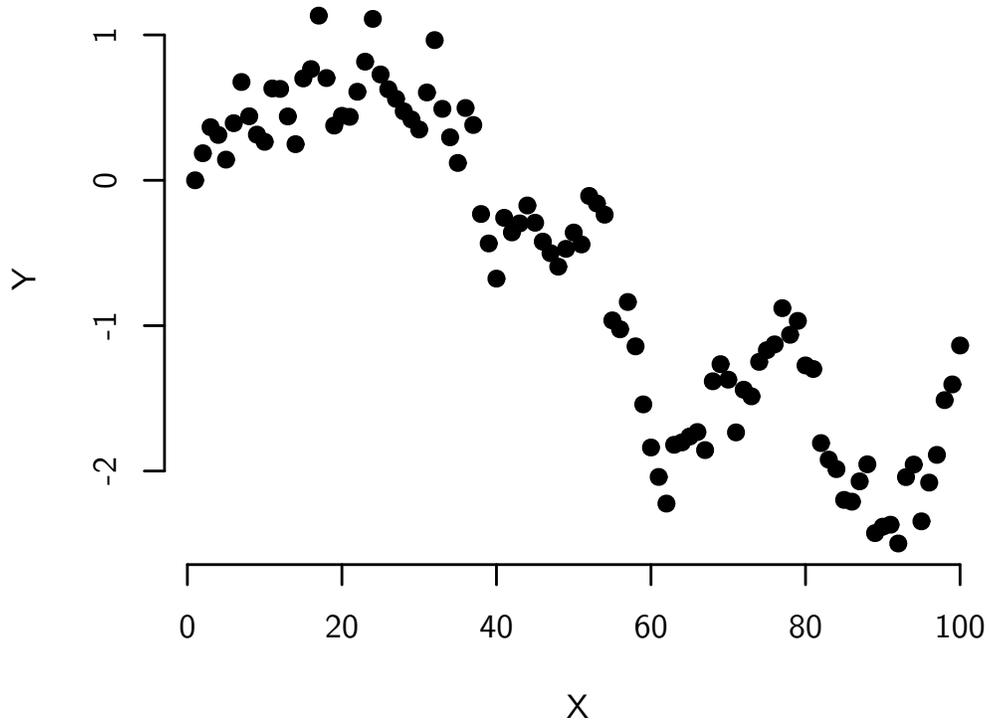
. This assumption is less stringent because we it allow us to **transform** the independent variable in arbitrary ways without violating linearity, so that the following is **not** a violation of the linearity assumption:

$$Y_i = \beta_0 + \beta_1 X_i^2 + u_i$$

*Assumption 2: Random Sample*

**Assumption 2** - We have a iid random sample of size  $n$ ,  $\{(Y_i, X_i) : i = 1, 2, \dots, n\}$  from the population regression model above.

This is random sampling assumption we've always maintained. Violations of this assumption would include time-series and selected samples.



Think about the weight example from last week, where  $Y_i$  was my weight on a given day and  $X_i$  was my number of active minutes the day before:

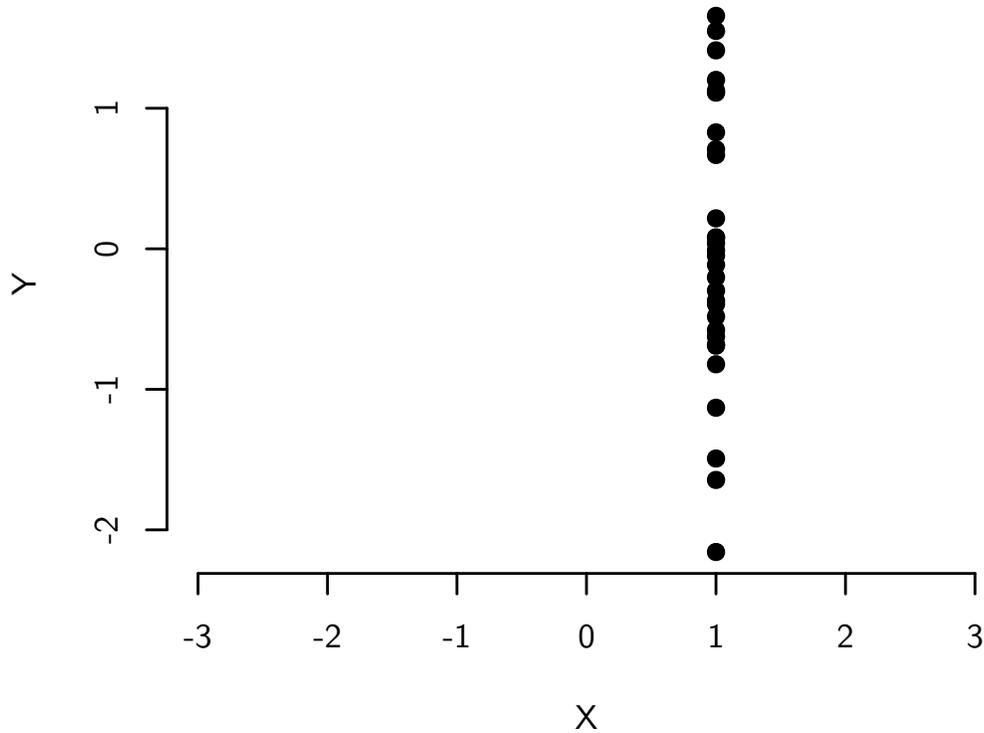
$$\text{weight}_i = \beta_0 + \beta_1 \text{activity}_i + u_i$$

What if I only weighed myself on the weekdays? This would obviously be a selected sample because I weigh more on the weekends.

*Assumption 3: Variation in X*

**Assumption 3** - The in-sample independent variables,  $\{X_i : i = 1, \dots, n\}$ , are not all the same value.

Why does this matter? How would you draw the line of best fit through this scatterplot, which is a violation of this assumption?



Also remember the formula for the OLS slope estimator and think about what happens here when  $X_i$  doesn't vary?

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})}{\sum_{i=1}^n (X_i - \bar{X})^2}$$

*Assumption 4: Zero conditional mean of the errors*

**Assumption 4** - The error,  $u_i$ , has expected value of 0 given any value of the independent variable:

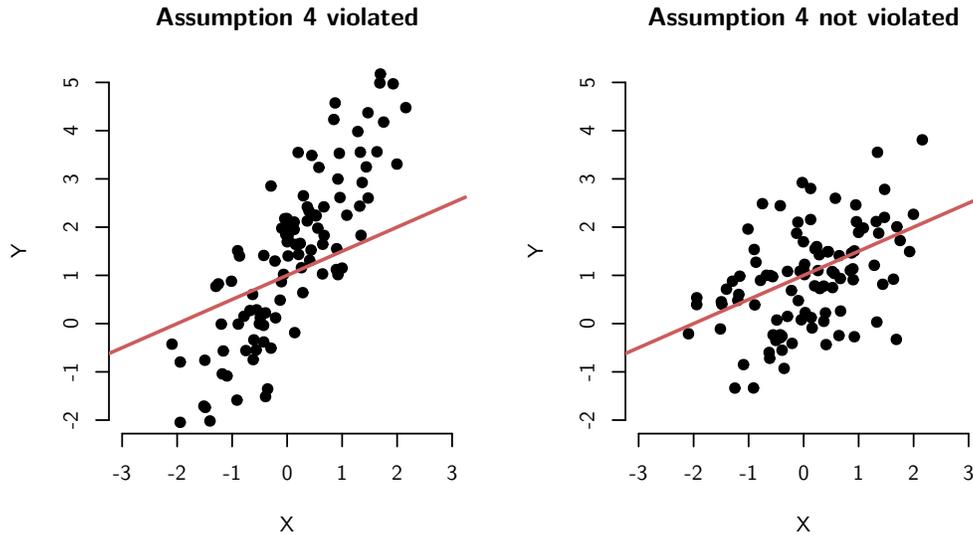
$$\mathbb{E}[u_i | X_i = x] = 0 \quad \forall x.$$

This is the key assumption about causality in the model. It says that the average of all the other stuff that affects  $Y_i$  except  $X_i$  is the same at every level of  $X_i$ . How does this assumption get violated? Let's generate data from the following model:

$$Y_i = 1 + 0.5X_i + u_i$$

But let's compare two situations. One where  $X_i$  and  $u_i$  are correlated so that the mean of  $u_i$  depends on  $X_i$  (a violation of Assumption 4) and one where there is no correla-

tion (not a violation). Let's plot this data along with the true regression line ( $\beta_0 = 1$  and  $\beta_1 = 0.5$ ):



For the violation, you can see that for low values of  $X_i$  most of the errors are negative and for high values of  $X_i$ , most of the errors are positive. You can also see that the sample of data points doesn't really fit the regression line at all. Compare this to a situation with no correlation between  $X_i$  and  $u_i$ , where the errors are roughly 0 on average, no matter the value of  $X_i$ .

Think about the weight example from last week, where  $Y_i$  was my weight on a given day and  $X_i$  was my number of active minutes the day before:

$$\text{weight}_i = \beta_0 + \beta_1 \text{activity}_i + u_i$$

What might in  $u_i$  here? Amount of food eaten, workload, etc etc. We have to assume that all of these factors have the same mean, no matter what my level of activity was. Plausible? Probably not.

When is this assumption most plausible? When  $X_i$  is randomly assigned in experimental data. In an experiment, we assign  $X_i$ , so we can ensure that it is unrelated to the  $u_i$  by design. When we have **observational data** where we observe  $X_i$  instead of assigning it, it will be very difficult to justify this assumption. This is because we will have to trust that whoever did assign/choose/set the level of  $X_i$  did so in a process unrelated to all the other factors that affect  $u_i$ .

With Assumptions 1-4, we can show that the OLS estimator for the slope is unbiased, that is  $\mathbb{E}[\hat{\beta}_1] = \beta_1$ . There are two ways that we use the above assumptions. First,

we can establish that the conditional expectation function (CEF)

$$\begin{aligned}
 \mathbb{E}[Y_i|X_1, \dots, X_n] &= \mathbb{E}[Y_i|X_i] && \text{(A2: iid)} \\
 &= \mathbb{E}[\beta_0 + \beta_1 X_i + u_i|X_i] && \text{(A1: linearity)} \\
 &= \beta_0 + \beta_1 X_i + \mathbb{E}[u_i|X_i] \\
 &= \beta_0 + \beta_1 X_i && \text{(A4: zero mean error)}
 \end{aligned}$$

Second, note that we can only calculate  $\widehat{\beta}_1$  when Assumption 3 (variation in  $X$ ) holds.

With these two facts, we can show that  $\mathbb{E}[\widehat{\beta}_1|X_1, \dots, X_n] = \beta_1$ . Remember that we showed that  $\widehat{\beta}_1 = \sum_{i=1}^n W_i Y_i$ . We're going to use this fact. Also remember that  $W_i$  is a function of all observations of the independent variable since it contains the mean, so conditional on  $\mathbf{X} = (X_1, \dots, X_n)$ , it is constant.

$$\begin{aligned}
 \widehat{\beta}_1 &= \sum_{i=1}^n W_i Y_i \\
 &= \sum_{i=1}^n W_i (\beta_0 + \beta_1 X_i + u_i) && \text{(linearity)} \\
 &= \beta_0 \sum_{i=1}^n W_i + \beta_1 \sum_{i=1}^n W_i X_i + \sum_{i=1}^n W_i u_i
 \end{aligned}$$

Are we stuck? No! Because we can show that  $\sum_{i=1}^n W_i = 0$  and  $\sum_{i=1}^n W_i X_i = 1$ :

$$\begin{aligned}
 \sum_{i=1}^n W_i &= \sum_{i=1}^n \frac{(X_i - \bar{X})}{\sum_{i=1}^n (X_i - \bar{X})^2} \\
 &= \frac{1}{\sum_{i=1}^n (X_i - \bar{X})^2} \sum_{i=1}^n (X_i - \bar{X}) \\
 &= \frac{1}{\sum_{i=1}^n (X_i - \bar{X})^2} \cdot 0 = 0
 \end{aligned}$$

- This works because the sum of deviations from the mean are 0! Now, the second

fact:

$$\begin{aligned}
 \sum_{i=1}^n W_i X_i &= \sum_{i=1}^n \frac{X_i(X_i - \bar{X})}{\sum_{i=1}^n (X_i - \bar{X})^2} \\
 &= \frac{1}{\sum_{i=1}^n (X_i - \bar{X})^2} \sum_{i=1}^n X_i(X_i - \bar{X}) \\
 &= \frac{1}{\sum_{i=1}^n (X_i - \bar{X})^2} \left[ \sum_{i=1}^n X_i(X_i - \bar{X}) - \sum_{i=1}^n \bar{X}(X_i - \bar{X}) \right] \\
 &= \frac{1}{\sum_{i=1}^n (X_i - \bar{X})^2} \sum_{i=1}^n (X_i - \bar{X})(X_i - \bar{X}) \\
 &= 1
 \end{aligned}$$

Plugging this back into our original derivation, we get the following:

$$\hat{\beta}_1 = \beta_0 \cdot 0 + \beta_1 \cdot 1 + \sum_i W_i u_i = \beta_1 + \sum_{i=1}^n W_i u_i$$

To show unbiasedness, we just need to take conditional expectations:

$$\begin{aligned}
 \mathbb{E}[\hat{\beta}_1 | X_1, \dots, X_n] &= \mathbb{E}[\beta_1 + \sum_{i=1}^n W_i u_i | X_1, \dots, X_n] \\
 &= \beta_1 + \sum_{i=1}^n \mathbb{E}[W_i u_i | X_1, \dots, X_n] \\
 &= \beta_1 + \sum_{i=1}^n W_i \mathbb{E}[u_i | X_1, \dots, X_n] \quad (W_i \text{ is a function of } X_i) \\
 &= \beta_1 + \sum_{i=1}^n W_i \cdot 0 \quad (\text{iid} + \text{zero conditional mean error}) \\
 &= \beta_1
 \end{aligned}$$

Now, noticed that we conditioned on  $X_1, \dots, X_n$ . But we need to show that  $\mathbb{E}[\hat{\beta}_1] = \beta_1$ . Let's use the law of iterated expectations!

$$\begin{aligned}
 \mathbb{E}[\hat{\beta}_1] &= \mathbb{E}[\mathbb{E}[\hat{\beta}_1 | X_1, \dots, X_n]] \\
 &= \mathbb{E}[\beta_1] \\
 &= \beta_1
 \end{aligned}$$

The basic intuition here that the conditional mean given the independent variable is the same, no matter the value of the independent variables. Therefore, the overall mean must just be equal to that constant.

So to recap: if we assume linearity, random sampling, variation in  $X$ , and zero conditional mean for the error, then the OLS estimator will be unbiased.

### Consistency

Under the same set of assumptions, we can show that the OLS estimator is consistent, so that  $\hat{\beta}_1 \xrightarrow{p} \beta_1$ . In fact, this is true under a weakening of Assumption 4.

**Assumption 4(b)** - The error has following two properties:  $\mathbb{E}[u_i] = 0$  and  $\mathbb{E}[u_i X_i] = 0$ .

The first part of this assumption, that the errors have unconditional mean 0, is not really an assumption if we include an intercept in our model. The second part is more restrictive since it essentially says that the errors are **uncorrelated** with the independent variable. This is weaker than the earlier zero conditional mean error, since it only rules out linear relationships between the errors and  $X_i$ . Assumption 4' allows for nonlinearities in that relationship. This assumption is problematic in the sense that it means that population regression function we have modeled does not capture the CEF, but rather the best linear approximation to the CEF. Thus, this assumption says that even if we don't get the linear model quite right—there are unmeasured nonlinear relationships—we can still get consistent estimates of the population line of best fit.

Consistency is actually very easy to prove once we note the following property of  $\hat{\beta}_1$ :

$$\hat{\beta}_1 = \beta_1 + \sum_{i=1}^n W_i u_i$$

It can be shown that the estimation error will converge in probability to the following:

$$\sum_{i=1}^n W_i u_i \xrightarrow{p} \frac{\text{Cov}(X_i, u_i)}{\mathbb{V}[X_i]}$$

Consistency follows from the fact that under Assumption 4(b), the covariance of the error and  $X_i$  will be 0 and so  $\hat{\beta}_1 \xrightarrow{p} \beta_1$ . Note that assumes that the variance of  $X_i$  is non-zero.

Where are we?

Now we know that, under Assumptions 1-4, we know that  $\hat{\beta}_1 \sim ?(\beta_1, ?)$ . That is we know that the sampling distribution is centered on the true population slope, but we don't know the population variance. In order to derive the sampling variance of the OLS estimator, it is typical to make one additional assumption. This assumption isn't strictly need to derive the sampling variance of the OLS estimator, but it makes the derivation much easier and almost all statistical software packages report standard errors based on this assumption. So it's useful to understand it.

*Assumption 5: Homoskedasticity*

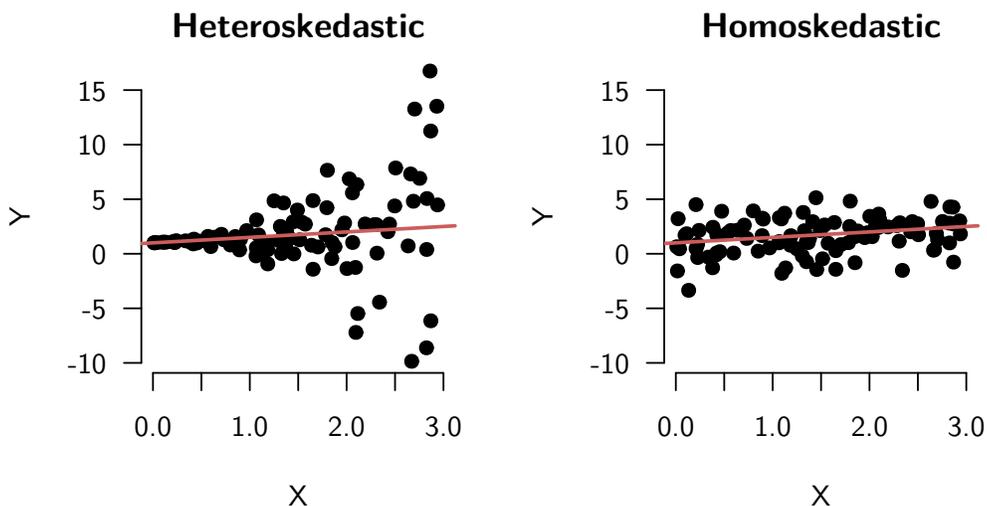
**Assumption 5** - The conditional variance of  $Y_i$  given  $X_i$  is constant:

$$\mathbb{V}(Y_i | X_i = x) = \mathbb{V}(u_i | X_i = x) = \sigma_u^2.$$

The conditional variance of  $Y$  given  $X$  is sometimes called the **skedastic function**,

thus the name homoskedasticity.

Violations of this assumption will be when the variance of the  $u_i$  is difference at different levels of  $X_i$ . For example, in the follow two example, the left plot show a **heteroskedastic** situation. As  $X_i$  increases, so does the variance of  $Y_i$ . In the right plot, the variance is constant.



Let's derive the sampling variance under the homoskedasticity assumption. First, remember that  $\hat{\beta}_1 = \beta_1 + \sum_{i=1}^n W_i u_i$  and that the variance of the estimator will

only be a function of the second part of this sum since  $\beta_1$  is constant. So we have the following:

$$\begin{aligned}
 \mathbb{V}[\widehat{\beta}_1 | X_1, \dots, X_n] &= \mathbb{V} \left[ \sum_{i=1}^n W_i u_i \mid X_1, \dots, X_n \right] \\
 &= \sum_{i=1}^n W_i^2 \mathbb{V}[u_i | X_1, \dots, X_n] && \text{(A2: iid)} \\
 &= \sum_{i=1}^n W_i^2 \mathbb{V}[u_i | X_i] && \text{(A2: iid)} \\
 &= \sigma_u^2 \sum_{i=1}^n W_i^2 && \text{(A5: homoskedastic)} \\
 &= \frac{\sigma_u^2 \sum_{i=1}^n (X_i - \bar{X})^2}{\left( \sum_{i=1}^n (X_i - \bar{X})^2 \right)^2} \\
 &= \frac{\sigma_u^2}{\sum_{i=1}^n (X_i - \bar{X})^2}
 \end{aligned}$$

So what drives the sampling variability of the OLS estimator?

- The higher the variance of  $Y_i$ , the higher the sampling variance
- The lower the variance of  $X_i$ , the higher the sampling variance
- As we increase  $n$ , the denominator gets large, while the numerator is fixed and so the sampling variance shrinks to 0.

But we don't observe  $\sigma_u^2$ —it is the variance of the errors, which we don't observe. What can we do? Estimate it using the residuals!

$$\widehat{\sigma}_u^2 = \frac{1}{n-2} \sum_{i=1}^n \widehat{u}_i^2$$

Here we use  $n-2$  instead of  $n$  or  $n-1$ . Why is that? Remember that OLS is designed to minimize the sum of the squared residuals, so it tends to slightly underestimate the variance. The  $n-2$  corrects this. With this, we can find the estimated standard error of our OLS estimator of the slope:

$$\widehat{SE}[\widehat{\beta}_1] = \frac{\sqrt{\widehat{\sigma}_u^2}}{\sqrt{\sum_{i=1}^n (X_i - \bar{X})^2}} = \frac{\widehat{\sigma}_u}{\sqrt{\sum_{i=1}^n (X_i - \bar{X})^2}}$$

### Gauss-Markov Theorem

**Theorem** Under assumptions 1-5, the OLS estimator is BLUE, or the Best Linear Unbiased Estimator, where by “best” we mean it lowest sampling variance.

The proof is very detailed, so we’ll skip it. See Wooldridge, Appendix 3A.6 for details. Fails to hold when the assumptions are violated!

### Asymptotic normality of OLS

Remember that we can write  $\hat{\beta}_1 - \beta_1 = \sum_{i=1}^n W_i u_i$ , so that the estimation error for the OLS estimator is the sum of i.i.d. mean 0 r.v.s. Also remember the mantra of the central limit theorem: “the sums and means of r.v.’s tend to be Normally distributed in large samples.” Applying the CLT here, we know that in large samples:

$$\frac{\hat{\beta}_1 - \beta_1}{SE[\hat{\beta}_1]} \xrightarrow{d} N(0, 1)$$

Also, in large samples, remember that we can replace the true standard error with our estimate of the standard error, so that:

$$\frac{\hat{\beta}_1 - \beta_1}{\widehat{SE}[\hat{\beta}_1]} \xrightarrow{d} N(0, 1)$$

## HYPOTHESIS TESTS FOR REGRESSION

- Null:  $H_0 : \beta_1 = 0$ 
  - The null is the straw man we want to knock down.
  - With regression, almost always null of no relationship
- Alternative:  $H_a : \beta_1 \neq 0$ 
  - Claim we want to test
  - Almost always “some effect”
  - Could do one-sided test, but you shouldn’t, for reasons we’ve already discussed

Under the null of  $H_0 : \beta_1 = c$ , we can use the following familiar test statistic:

$$T = \frac{\hat{\beta}_1 - c}{\widehat{SE}[\hat{\beta}_1]}.$$

In large samples, we know that  $T$  is approximately (standard) Normal. Thus, under the null and in large samples, we know the distribution of  $T$  and can use that to formulate

a rejection region and calculate p-values. We can use the Wald/t-test we developed a few weeks ago for asymptotically normal estimators. Everything is the same. For instance, for an  $\alpha = 0.05$  test, we can reject the null when  $|T| > 1.96$ .

### R output

By default, R shows you the  $T_{obs}$  for the test statistic with the null of  $\beta_1 = 0$ , which is just the estimate divided by the standard error:

$$T_{obs} = \frac{\hat{\beta}_1 - 0}{\widehat{SE}[\hat{\beta}_1]} = \frac{\hat{\beta}_1}{\widehat{SE}[\hat{\beta}_1]}$$

This is often referred to as **the t-statistic**. R also calculates the p-values for you. In the AJR data, for example:

```
out <- lm(logpgp95 ~ logem4, data = ajr)
coef(summary(out))

##              Estimate Std. Error  t value    Pr(>|t|)
## (Intercept) 10.6602465  0.30528441  34.919066  8.758878e-50
## logem4      -0.5641215  0.06389003  -8.829569  2.093611e-13
```

## CONFIDENCE INTERVALS FOR REGRESSION

Large-sample confidence intervals are almost exactly the same as in the sample means case. We can find the critical values using the same procedure so that, for instance, a 95% large-sample confidence interval for  $\beta_1$  is just

$$\hat{\beta}_1 \pm 1.96\widehat{se}[\hat{\beta}_1].$$

More generally, for a particular  $100(1 - \alpha)\%$  confidence interval, we use the following formula for the confidence interval:

$$\hat{\beta}_1 \pm z_{\alpha/2}\widehat{se}[\hat{\beta}_1]$$

Confidence intervals are not outputted by default in R, but you grab them for any regression using the `confint()` function:

```
confint(lm(logpgp95 ~ logem4, data = ajr))

##              2.5 %      97.5 %
## (Intercept) 10.0525931 11.2678999
## logem4      -0.6912914 -0.4369515
```

## GOODNESS OF FIT

### *Prediction error*

How do we judge how well a line fits the data? Is there some way to judge? One way is to find out how much better we do at predicting  $Y$  once we include  $X$  into the regression model. Prediction errors without  $X$ : best prediction is the mean, so our squared errors, or the **total sum of squares** ( $SS_{tot}$ ) would be:

$$SS_{tot} = \sum_{i=1}^n (Y_i - \bar{Y})^2$$

Once we have estimated our model, we have new prediction errors, which are just the sum of the squared residuals or  $SS_{res}$ :

$$SS_{res} = \sum_{i=1}^n (Y_i - \hat{Y}_i)^2$$

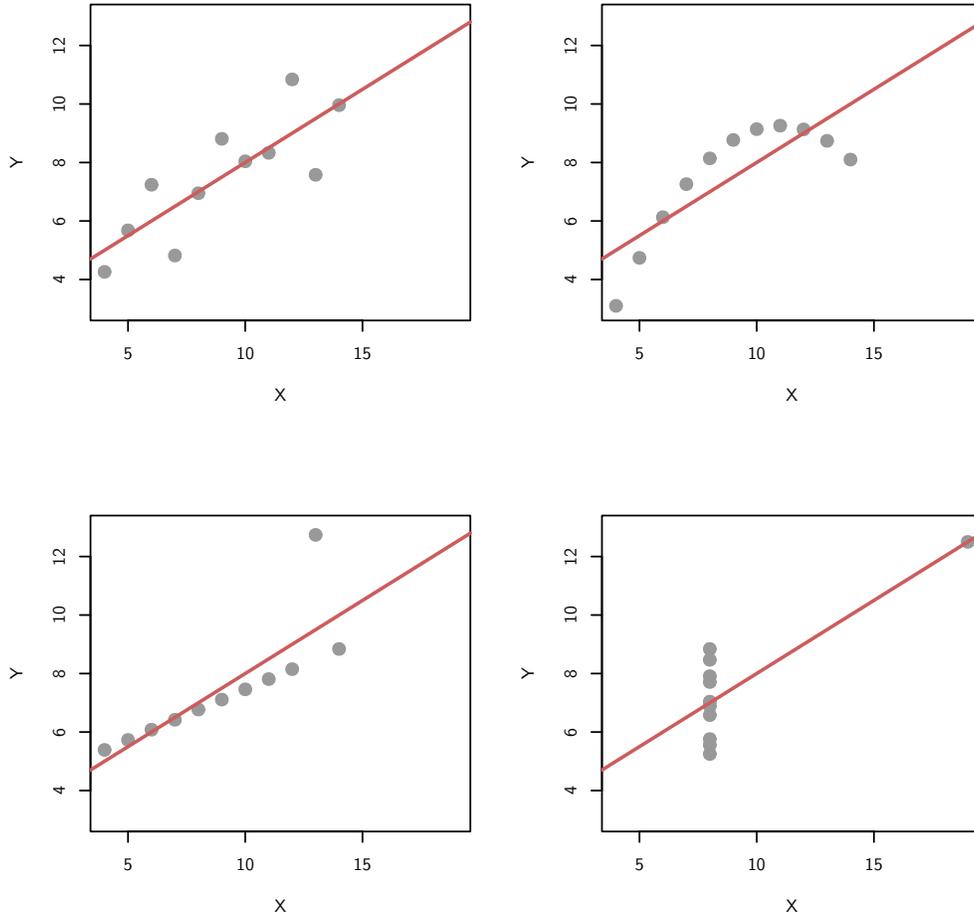
By definition, the residuals have to be smaller than the deviations from the mean, so we might ask the following: how much lower is the  $SS_{res}$  compared to the  $SS_{tot}$ ?

We quantify this question with the **coefficient of determination** or  $R^2$ . This is the following:

$$R^2 = \frac{SS_{tot} - SS_{res}}{SS_{tot}} = 1 - \frac{SS_{res}}{SS_{tot}}$$

This is the fraction of the total prediction error eliminated by providing information on  $X$ . Alternatively, this is the fraction of the variation in  $Y$  is “explained by”  $X$ . So,  $R^2 = 0$  means no relationship at all, and  $R^2 = 1$  implies perfect linear fit.

Unforutnately, the  $R^2$  can be very misleading. Each of the following samples have the same  $R^2$  even though they are vastly different:



### SMALL-SAMPLE MODEL-BASED INFERENCE

The testing and confidence intervals above depended on a large-sample approximation. What if we have a small sample? What can we do then? First, we still know that, conditional on  $X_i$ ,  $\hat{\beta} \sim (\beta_1, SE[\hat{\beta}]^2)$  since we know that unbiasedness holds and we know how to calculate the sampling variance. We just don't know the form of the sampling distribution. Can't get something for nothing, but we can make progress if we make another assumption: 1. Linearity 2. Random (iid) sample 3. Variation in  $X_i$  4. Zero conditional mean of the errors 5. Homoskedasticity 6. Errors are conditionally Normal

*Assumption 6: conditionally Normal errors*

**Assumption 6** - The conditional distribution of  $u$  given  $X$  is Normal with mean 0 and variance  $\sigma_u^2$ .

This implies that the distribution of  $Y_i$  given  $X_i$  is:  $N(\beta_0 + \beta_1 X_i, \sigma_u^2)$ . Under this assumption, we know that for any sample size:

$$\frac{\hat{\beta}_1 - \beta_1}{SE[\hat{\beta}_1]} \sim N(0, 1)$$

Furthermore, if we replace the true standard error with the estimated standard error, then we get the following:

$$\frac{\hat{\beta}_1 - \beta_1}{\widehat{SE}[\hat{\beta}_1]} \sim t_{n-2}$$

The standardized coefficient follows a  $t$  distribution  $n - 2$  degrees of freedom. We take off an extra degree of freedom because we had to one more parameter than just the sample mean. All of this depends on Normal errors! Of course, we can check to see if the error do look Normal.

*Review of assumptions*

- What assumptions do we need to make what claims with OLS?
  1. Data description: variation in  $X$
  2. Consistency: linearity, iid, variation in  $X$ , uncorrelated error.
  3. Unbiasedness: linearity, iid, variation in  $X$ , zero conditional mean error.
  4. Large-sample inference: linearity, iid, variation in  $X$ , zero conditional mean error, homoskedasticity.
  5. Small-sample inference: linearity, iid, variation in  $X$ , zero conditional mean error, homoskedasticity, Normal errors.

## APPENDIX

*Proof of sums and means trick*

- In the derivation of the OLS estimator, we relied on a trick with the means and sums. Here is the proof:

$$\begin{aligned}
\sum_{i=1}^n X_i(Y_i - \bar{Y}) &= \sum_{i=1}^n X_i(Y_i - \bar{Y}) - n\bar{X}\bar{Y} + n\bar{X}\bar{Y} \\
&= \sum_{i=1}^n X_i(Y_i - \bar{Y}) - \bar{X} \left( \sum_{i=1}^n Y_i \right) + \bar{X} \left( \sum_{i=1}^n \bar{Y} \right) \\
&= \sum_{i=1}^n X_i(Y_i - \bar{Y}) - \bar{X} \left( \sum_{i=1}^n Y_i - \sum_{i=1}^n \bar{Y} \right) \\
&= \sum_{i=1}^n X_i(Y_i - \bar{Y}) - \bar{X} \sum_{i=1}^n (Y_i - \bar{Y}) \\
&= \sum_{i=1}^n X_i(Y_i - \bar{Y}) - \sum_{i=1}^n \bar{X} (Y_i - \bar{Y}) \\
&= \sum_{i=1}^n [X_i(Y_i - \bar{Y}) - \bar{X} (Y_i - \bar{Y})] \\
&= \sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})
\end{aligned}$$

- Replace  $(Y_i - \bar{Y})$  with  $(X_i - \bar{X})$  to prove that

$$\sum_{i=1}^n X_i(X_i - \bar{X}) = \sum_{i=1}^n (X_i - \bar{X})^2$$